

# Large and Moderate Deviation Principles for path-distribution dependent SDEs

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Joint work with Xinyi Gu

- 1 Introduction
- 2 Main Results

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- Denote by  $\mathcal{P}$  the collection of all probability measures on  $\mathbb{R}^d$ . Assume  $b : [0, \infty) \times \mathbb{R}^d \times \mathcal{P} \rightarrow \mathbb{R}^d$  and  $\sigma : [0, \infty) \times \mathbb{R}^d \times \mathcal{P} \rightarrow \mathbb{R}^d \otimes \mathbb{R}^d$  are measurable functions.

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Consider

$$dX^\epsilon(t) = b(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dt + \sqrt{\epsilon}\sigma(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dW(t), \quad t \in [0, T]$$

with initial data  $X^\epsilon(0) = x$ .

Under appropriate assumptions, as  $\epsilon \rightarrow 0$ ,  $X^\epsilon$  will tend to the solution of the following deterministic equation:

$$\begin{cases} dX^0(t) = b(t, X^0(t), \delta_{X^0(t)})dt, & t \in [0, T], \\ X^0(0) = x, \end{cases} \quad (1)$$

where  $\delta_{X^0(t)}$  is a dirac measure at  $X^0(t)$ .

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- Large deviation principle(LDP):  $\lambda(\epsilon) = \frac{1}{\sqrt{\epsilon}}$ ;
- Central limit theorem(CLT):  $\lambda(\epsilon) = 1$ ;
- Moderate deviation principle(MDP):

$$\lambda(\epsilon) \rightarrow +\infty, \quad \sqrt{\epsilon}\lambda(\epsilon) \rightarrow 0 \text{ as } \epsilon \rightarrow 0.$$

Assume  $\mathcal{E}$  is a Polish space and  $\mathcal{B}(\mathcal{E})$  is the Borel  $\sigma$ -algebra.  $\{Z^\epsilon\}_{\epsilon>0}$  is a family of  $\mathcal{E}$ -valued random variables.

## Definition (Rate function)

A function  $I : \mathcal{E} \rightarrow [0, \infty]$  is called a rate function on  $\mathcal{E}$ , if for each  $\alpha \in [0, \infty)$ , the level set  $\{x \in \mathcal{E} : I(x) \leq \alpha\}$  is a compact subset of  $\mathcal{E}$ .

## Definition (Large deviation principle)

Let  $I$  be a rate function on  $\mathcal{E}$ . The family  $\{Z^\epsilon\}_{\epsilon>0}$  is said to satisfy a large deviation principle on  $\mathcal{E}$  with rate function  $I$ , if the following two conditions are satisfied:

- ① (Upper bound) For every closed subset  $C$  of  $\mathcal{E}$ ,

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(Z^\epsilon \in C) \leq - \inf_{x \in C} I(x).$$

- ② (Lower bound) For every open subset  $O$  of  $\mathcal{E}$ ,

$$\liminf_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(Z^\epsilon \in O) \geq - \inf_{x \in O} I(x).$$

## LDP for mean-field interacting particle systems:

- (1) S. Feng, Large deviations for empirical process of mean-field interacting particle system with unbounded jumps. *Ann. Probab.*, 22(1994), no.4, 2122-2151.
- (2) S. Feng, Large deviations for Markov processes with mean field interaction and unbounded jumps. *Probab. Theory Related Fields*, 100(1994), no. 2, 227-252.
- (3) W. Liu and L. Wu, Large deviations for empirical measures of mean-field gibbs measures. *Stoch. Proc. Appl.*, 130 (2020), 503-520.

LDP and MDP on  $(C([0, T]; \mathbb{R}^d), \|\cdot\|_\infty)$ :

- (1) G. Dos Reis, W. Salkeld, and J. Tugaut, Freidlin-Wentzell LDPs in path space for McKean-Vlasov equations and the functional iterated logarithm law. *Ann. Appl. Probab.*, **29**(2019), 1487-1540.
- (2) Y. Suo and C. Yuan, CLT and MDP for McKean-Vlasov SDEs. *Acta Appl. Math.*, 175(2021), Paper No.16.
- (3) D. Adams, G.D. Reis, R. Ravaille, W. Salkeld and J. Tugaut, Large Deviations and Exit-times for reflected McKean-Vlasov equations with self-stabilizing terms and superlinear drifts. *Stoch. Proc. Appl.*, 146(2022), 264-310.



# Known Results

Idea of the existing results: Recall

$$dX^\epsilon(t) = b(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dt + \sqrt{\epsilon}\sigma(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dW(t), \quad t \in [0, T],$$

and

$$dX^0(t) = b(t, X^0(t), \delta_{X^0(t)})dt, \quad t \in [0, T],$$

with initial data  $X^\epsilon(0) = X^0(0) = x$ .

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with initial data  $Z^\epsilon(0) = x$ .

Two steps:

- **Step 1:** LDPs for  $Z^\epsilon$  as the parameter  $\epsilon$  tends to 0,
- **Step 2:**  $X^\epsilon$  and  $Z^\epsilon$  are exponentially equivalent as  $\epsilon$  goes to 0, i.e. for any  $\delta > 0$ ,

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(\|X^\epsilon - Z^\epsilon\|_\infty \geq \delta) = -\infty.$$

- (4) W. Liu, Y. Song, J. Zhai, T. Zhang: Large and moderate deviation principles for McKean-Vlasov SDEs with jumps, to appear in *Potential Analysis*
- (5) W. Hong, S. Li, and W. Liu: Large deviation principle for McKean-Vlasov quasilinear stochastic evolution equations. *Appl. Math. Optim.*, 84(2021), no. 1, suppl., S1119-S1147.

# Known Results

The key step is to identify the correct controlled equation.

Assume that there is a unique strong solution  $X^\epsilon$ .

$$dX^\epsilon(t) = b(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dt + \sqrt{\epsilon}\sigma(t, X^\epsilon(t), \mathcal{L}_{X^\epsilon(t)})dW(t), \quad t \in [0, T]$$

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with  $X^\epsilon(0) = x$ .

Then, there exists a measurable map  $\Gamma^\epsilon$  such that the solution  $X^\epsilon$  can be represented as

$$X^\epsilon = \Gamma^\epsilon(W(\cdot)).$$

$X^{\epsilon, h^\epsilon} := \Gamma^\epsilon \left( W(\cdot) + \frac{1}{\sqrt{\epsilon}} \int_0^\cdot u^\epsilon(s) ds \right)$  is the solution to the following controlled SDE:

$$\begin{aligned} dX^{\epsilon, u^\epsilon}(t) &= b(t, X^{\epsilon, u^\epsilon}(t), \mathcal{L}_{X^{\epsilon, u^\epsilon}(t)})dt + \sqrt{\epsilon}\sigma(t, X^{\epsilon, u^\epsilon}(t), \mathcal{L}_{X^{\epsilon, u^\epsilon}(t)})dW(t) \\ &\quad + \sigma(t, X^{\epsilon, u^\epsilon}(t), \mathcal{L}_{X^{\epsilon, u^\epsilon}(t)})u^\epsilon(t)dt, \quad t \in [0, T], \end{aligned}$$

where  $\mathcal{L}_{X^{\epsilon, u^\epsilon}(t)}$  is the distribution of  $X^{\epsilon, u^\epsilon}(t)$ , but not the one of  $X^\epsilon(t)$ .

A. Matoussi, W. Sabbagh, T. Zhang, Large deviation principle of obstacle problems for Quasilinear Stochastic PDEs. *Appl. Math. Optim.*, 83(2021), no.2, 849-879.

(LDP1) For any  $m \in (0, \infty)$ , any family  $\{u_\epsilon, \epsilon > 0\} \subset \mathcal{S}^m$ , and any  $\delta > 0$ ,

$$\lim_{\epsilon \rightarrow 0} \mathbb{P} \left( \|X^{\epsilon, u_\epsilon} - \Gamma^0(u_\epsilon)\|_\infty > \delta \right) = 0.$$

(LDP2) For any  $m \in (0, \infty)$  and any family  $\{u_n \in \mathcal{S}^m, n \in \mathbb{N}\}$  satisfying that  $u_n$  converges to some element  $u$  in  $\mathcal{S}^m$  as  $n \rightarrow \infty$ ,  $\Gamma^0(u_n)$  converges to  $\Gamma^0(u)$  in the space  $C([0, T]; \mathbb{R}^d)$ .

LDP on  $(C^\alpha([0, T]; \mathbb{R}^d), \|\cdot\|_\alpha)$ :

- 1 P. Baldi, G. Ben Arous, and G. Kerkycharian, Large deviations and the Strassen theorem in Hölder norm. *Stochastic Process. Appl.* 42(1992), no.1, 171-180.
- 2 G. Ben Arous and M. Ledoux, Grandes déviations de Freidlin-Wentzell en norme Hölderienne. In *Séminaire de Probabilités, XXVIII. Lecture Notes in Math.*, 1583(1994), 293-299. Springer, Berlin.
- 3 Y.-J. Hu, A large deviation principle for small perturbations of random evolution equations in Hölder norm. *Stochastic Process. Appl.* 68(1997), 83-99.
- 4 F. Gao, Large deviations for diffusion processes in Hölder norm. *Adv. in Math. (China)*, 26(1997), no.2, 147-158.
- 5 G. Dos Reis, W. Salkeld, and J. Tugaut, Freidlin-Wentzell LDPs in path space for McKean-Vlasov equations and the functional iterated logarithm law. *Ann. Appl. Probab.*, **29**(2019), 1487-1540.



**Idea of the existing results:** Two steps to establish LDP on Hölder space:

- **Step 1:** prove LDPs on  $C([0, T]; \mathbb{R}^d)$ .
- **Step 2:** transfer LDP results from supremum norms to Hölder norms. To derive the following inequality: for each  $R > 0$  and  $\rho > 0$ , there exists  $\delta > 0$  and for  $\nu > 0$  such that for  $\epsilon \in (0, \nu)$ ,

$$\mathbb{P} \left( \|X^\epsilon - Y^u\|_\alpha \geq \rho, \|\sqrt{\epsilon}W - \int_0^\cdot u(s)ds\|_\infty \leq \delta \right) \lesssim \exp \left( -\frac{R}{\epsilon} \right).$$

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- For any fixed  $\tau > 0$ , denote by  $\mathcal{C} := C([- \tau, 0], \mathbb{R}^d)$  the space of all continuous  $\mathbb{R}^d$ -valued functions defined on  $[- \tau, 0]$ . It is equipped with the uniform norm

$$\|\xi\|_{\mathcal{C}} := \sup_{\theta \in [-\tau, 0]} |\xi(\theta)|.$$

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$$\|\xi\|_{\mathcal{C}} := \sup_{\theta \in [-\tau, 0]} |\xi(\theta)|.$$

- Let  $\mathcal{P}_2^{\mathcal{C}}$  be the collection of all probability measures with finite second moments on  $\mathcal{C}$ . It is equipped with

$$\mathbb{W}_2(\mu, \nu) := \inf_{\pi \in \Gamma(\mu, \nu)} \left( \int_{\mathcal{C} \times \mathcal{C}} \|\xi - \eta\|_{\mathcal{C}}^2 \pi(d\xi, d\eta) \right)^{\frac{1}{2}},$$

where  $\Gamma(\mu, \nu)$  denotes the set of all couplings for  $\mu$  and  $\nu$ .

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where  $\Gamma(\mu, \nu)$  denotes the set of all couplings for  $\mu$  and  $\nu$ .

- For  $f \in C([- \tau, T], \mathbb{R}^d)$ , the  $\mathcal{C}$ -valued function  $\{f_t\}_{t \in [0, T]}$  defined by

$$f_t(\theta) = f(t + \theta), \quad \theta \in [-\tau, 0]$$

is called the segment (or window) process of  $\{f(t)\}_{t \in [-\tau, T]}$ .

# Main Results

Path-distribution dependent SDEs:

Let  $b : [0, +\infty) \times \mathcal{C} \times \mathcal{P}_2^{\mathcal{C}} \rightarrow \mathbb{R}^d$  and  $\sigma : [0, +\infty) \times \mathcal{C} \times \mathcal{P}_2^{\mathcal{C}} \rightarrow \mathbb{R}^d \otimes \mathbb{R}^d$  be measurable functions.

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- Consider the following path-distribution dependent SDEs:

$$dX(t) = b(t, X_t, \mathcal{L}_{X_t})dt + \sigma(t, X_t, \mathcal{L}_{X_t})dW(t), \quad X_0 = \xi, \quad (2)$$

where  $\xi$  is an element of  $\mathcal{C}$ ,  $X_t$  is the segment process and  $\mathcal{L}_{X_t}$  stands for the distribution of  $X_t$ .

- Consider

$$dX^\epsilon(t) = b(t, X_t^\epsilon, \mathcal{L}_{X_t^\epsilon})dt + \sqrt{\epsilon}\sigma(t, X_t^\epsilon, \mathcal{L}_{X_t^\epsilon})dW(t), \quad X_0 = \xi \in \mathcal{C}.$$

- Let  $\{X^0(t)\}_{t \in [-\tau, T]}$  be the solution of

$$dX^0(t) = b(t, X_t^0, \delta_{X_t^0})dt, \quad X_0 = \xi \in \mathcal{C}.$$

# Main Results

## Assumptions:

(H1) (Continuity) For each  $t \geq 0$ ,  $b(t, \cdot, \cdot)$  is continuous on  $\mathcal{C} \times \mathcal{P}_2^{\mathcal{C}}$ , and there exists  $L > 0$  such that for  $t \geq 0$   $\xi, \eta \in \mathcal{C}$ ,  $\mu, \nu \in \mathcal{P}_2^{\mathcal{C}}$ ,

$$|b(t, \xi, \mu) - b(t, \eta, \nu)|^2 + \|\sigma(t, \xi, \mu) - \sigma(t, \eta, \nu)\|^2 \leq L (\|\xi - \eta\|_{\mathcal{C}}^2 + \mathbb{W}_2^2(\mu, \nu)).$$



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(H2) (Growth)  $b$  is bounded on bounded sets in  $[0, \infty) \times \mathcal{C} \times \mathcal{P}_2^{\mathcal{C}}$ , and there exists  $K > 0$  such that

$$|b(t, 0, \mu)|^2 + \|\sigma(t, 0, \mu)\|^2 \leq K (1 + \mu(\|\cdot\|_{\mathcal{C}}^2)), \quad t \geq 0, \mu \in \mathcal{P}_2^{\mathcal{C}}.$$

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(H3) For any  $t \in [0, T]$  and  $\mu \in \mathcal{P}_2$ ,  $b(t, \cdot, \mu) : \mathcal{C} \rightarrow \mathbb{R}^d$  is Frechet differentiable. There exists  $L' > 0$  such that

$$\|Db(t, x, \mu) - Db(t, x', \mu)\|_{\mathcal{C}^*} \leq L' \|x - x'\|_{\mathcal{C}}, \quad \forall x, x' \in \mathcal{C}, t \in [0, T], \mu \in \mathcal{P}_2$$

$$\text{and } \int_0^T \|Db(t, X_t^0, \delta_{X_t^0})\|_{\mathcal{C}^*} dt < \infty.$$

## Definition

A continuous adapted process  $\{X_t\}$  on  $\mathcal{C}$  is called a strong solution of (2), if

$$\int_0^t \mathbb{E}|b(s, X_s, \mathcal{L}_{X_s})|ds + \int_0^t \mathbb{E}\|\sigma(s, X_s, \mathcal{L}_{X_s})\|^2 ds < \infty, \quad t \geq 0$$

and  $X(t) := X_t(0)$  satisfies

$$X(t) = \xi(0) + \int_0^t b(s, X_s, \mathcal{L}_{X_s})ds + \int_0^t \sigma(s, X_s, \mathcal{L}_{X_s})dW_s, \quad t \geq 0.$$

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**Existence and Uniqueness of the Solution:** According to Theorem 3.1 in [1], under (H1) and (H2) there is a unique strong solution to (2).

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1. X. Huang, M. Röckner, F.-Y. Wang, Nonlinear Fokker-Planck equations for probability measures on path space and path-distribution dependent SDEs, *Discrete Contin. Dyn. Syst.*, 39(2019), 3017-3035.

# Main Results

For  $u \in L^2([0, T], \mathbb{R}^d)$ , let  $\{Y^u(t)\}_{t \in [-\tau, T]}$  be the solution of

$$\begin{cases} \frac{dY^u(t)}{dt} = b(t, Y_t^u, \delta_{X_t^0}) + \sigma(t, Y_t^u, \delta_{X_t^0})u(t), & t \in (0, T], \\ Y_0^u(t) = \xi(t), & t \in [-\tau, 0]. \end{cases} \quad (3)$$

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## Theorem 1 [Gu, S. 2022]

Assume **(H1)** and **(H2)** hold. Then  $\{X^\epsilon(\cdot)\}_{\epsilon > 0}$  satisfies a LDP on  $C([-\tau, T]; \mathbb{R}^d)$  with the speed  $\epsilon$  and the rate function  $I$  given by

$$I(g) = \inf_{\{u \in L^2([0, T], \mathbb{R}^d) : g = Y^u\}} \left\{ \frac{1}{2} \int_0^T |u(s)|^2 ds \right\}, \quad g \in C([-\tau, T], \mathbb{R}^d).$$

# Assumptions

Let  $a(\epsilon) > 0, \epsilon \in (0, 1)$  satisfy

$$a(\epsilon) \rightarrow +\infty, \quad \frac{\epsilon}{a(\epsilon)^2} \rightarrow 0, \quad \epsilon \rightarrow 0.$$

Define

$$M^\epsilon(t) := \frac{1}{a(\epsilon)} (X^\epsilon(t) - X^0(t)), \quad t \in [-\tau, T]$$

and for  $t \in [0, T]$

$$M_t^\epsilon(r) := M^\epsilon(t+r), \quad r \in [-\tau, 0].$$

# Main Result

For  $u \in S$ , let  $K^u$  be the solution of

$$\begin{cases} dK^u(t) = \mathcal{L}^* \langle Db(t, X_t^0, \delta_{X_t^0}), K_t^u \rangle \mathcal{L} dt + \sigma(t, X_t^0, \delta_{X_t^0}) u(t) dt, \\ K_0^u(t) = 0, \quad t \in [-\tau, 0]. \end{cases}$$



# Main Result

For  $u \in S$ , let  $K^u$  be the solution of

$$\begin{cases} dK^u(t) = \mathcal{L}^* \langle Db(t, X_t^0, \delta_{X_t^0}), K_t^u \rangle \mathcal{L} dt + \sigma(t, X_t^0, \delta_{X_t^0}) u(t) dt, \\ K_0^u(t) = 0, \quad t \in [-\tau, 0]. \end{cases}$$

## Theorem 2 [Gu, S. 2022]

Assume (H1), (H2) and (H3) hold. Then  $\{M^\epsilon(\cdot), \epsilon > 0\}$  satisfies a LDP on  $C([-\tau, T], \mathbb{R}^d)$  with speed  $\epsilon/a(\epsilon)$  and the rate function  $I$  given by

$$I(g) = \inf_{\{u \in L^2([0, T], \mathbb{R}^d) : g = K^u\}} \left\{ \frac{1}{2} \int_0^T |u(s)|^2 ds \right\}, \quad g \in C([-\tau, T], \mathbb{R}^d).$$

# Main Result

(H4)  $\sigma$  is bounded and there exists  $\beta \in (0, 1]$  such that for each  $y \in \mathcal{C}$  and  $\mu \in \mathcal{P}^{\mathcal{C}}$ ,  $b(\cdot, y, \mu)$  and  $\sigma(\cdot, y, \mu)$  are  $\beta$ -Hölder continuous.

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For a Borel set  $A$  of Hölder space  $C^\alpha([-\tau, 1]; \mathbb{R}^d)$ , denote

$$I(A) := \inf \left\{ \frac{1}{2} \int_0^1 |u(s)|^2 ds : Y^u \in A \right\}.$$

## Theorem 3[S. 2022]

Assume (H1), (H2) and (H4) hold. Let  $\alpha \in (0, \frac{1}{2})$  and  $\xi \in C^\alpha([-\tau, 0]; \mathbb{R}^d)$ . Then for each Borel set  $A$  of  $C^\alpha([-\tau, 1]; \mathbb{R}^d)$ ,

$$-I(\mathring{A}) \leq \liminf_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(X^\epsilon \in A) \leq \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(X^\epsilon \in A) \leq -I(\bar{A}),$$

where  $\mathring{A}$  and  $\bar{A}$  are the interior and closure of  $A$  in  $C^\alpha([-\tau, 1]; \mathbb{R}^d)$ .

## Proposition 4

Under the conditions of Theorem 3, for each  $R > 0$  and  $\rho > 0$ , there exists  $\delta > 0$  and for  $\nu > 0$  such that for  $\epsilon \in (0, \nu)$ ,

$$\mathbb{P} \left( \|X^\epsilon - Y^u\|_\alpha \geq \rho, \|\sqrt{\epsilon}W - \int_0^\cdot u(s)ds\|_\infty \leq \delta \right) \lesssim \exp \left( -\frac{R}{\epsilon} \right).$$

# Main Result

Let  $n$  be an integer and  $\{\bar{W}(t)\}_{t \in [0,1]}$  be a  $n$ -dimensional Brownian motion.

Lemma[G. Ben Arous, M. Ledoux 1994]

For  $\alpha \in (0, \frac{1}{2})$ , there exists a constant  $C > 0$  independent of  $n$  such that for  $u, v > 0$ ,

$$\mathbb{P}(\|\bar{W}\|_\alpha \geq u, \|\bar{W}\|_\infty \leq v) \leq C \max\left\{1, \left(\frac{u}{v}\right)^{\frac{1}{\alpha}}\right\} \exp\left\{-\frac{1}{C} \frac{u^{\frac{1}{\alpha}}}{v^{\frac{1}{\alpha}-2}}\right\}.$$

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Lemma[G. Ben Arous, M. Ledoux 1994]

For  $\alpha \in (0, \frac{1}{2})$ , there is a constant  $C' > 0$  such that for  $u > 0$  and  $K \in C([0, 1])$  with  $\|K\|_\infty \leq 1$ ,

$$\mathbb{P}\left(\left\|\int_0^\cdot K(s)dW(s)\right\|_\alpha \geq u, \|K\|_\infty \leq 1\right) \leq C' \exp\left\{-\frac{u^2}{C'}\right\}.$$

**Thanks for Your Attention.**